BioSecure Fusion Algorithm

Part II

1

Participants

Short name

- Tobias Scheidat (AMSL-BIO, U. of Magdeburg)
- Lorene Allano, Institut National des Télécommunications (GET-INT), France.
- Fernando Alonso, Universidad Autonoma de Madrid, (UPM), Spain
- O Fatukasi and N. Poh, U. of Surrey (UniS), UK.
- Harald Ganster, Joanneum Research (JR), Austria
- Albert Salah and Onkar Ambekar, Centrum voor Wiskunde en Informatica (CWI), the Netherlands
- John Baker, Johns Hopkins University Applied Physics Laboratory (JHUAPL), USA

Algorithms

AMSL-BIO

Weighted averaging

CET

- Sequential fusion strategy
- Gaussian mixture model

UPM

Linear logistic regression optimising a cost objective function

UniS

- Logistic regression in score/quality space
- quality based clustering fixed rule fusion
- naïve Bayes

JR

Dempster-Shafer fusion

CWI

Mixture of factor analysers

JHUAPL

Bayesian network

.

Two types of Algorithm

Conventional fusion

$$f: \mathbf{y} \to y_{com}$$

where $\mathbf{y} = [y_i, \dots, y_N]'$

Quality-dependent fusion

$$f: \mathbf{y}, \mathbf{q} \to y_{com}$$

where
$$\mathbf{q} = [\mathbf{q}_1, \dots, \mathbf{q}_N]'$$

and $\mathbf{q}_i \in \mathbb{R}^Q$

Naive Bayes (baseline) Logistic Regression, Fixed Rule and Device-specific Quality-dependent Fusion

Omalara Fatukasi and Norman Poh

University of Surrey (UniS)

Slide 5

Fusion Algorithms (UniS)

Baseline (Unis): Naive Bayes $y_{com} = \prod_{i} P(C|y_i)$ $P(C|y_i)$ is estimated using a linear logistic regression

UniS: Quality-dependent fusion

$$y_{LR} \equiv P(\mathbf{C}|\mathbf{x}) = \frac{1}{1 + \exp(-g(\mathbf{x}))}$$
 linear logistic regression where
$$g(\mathbf{x}) = \sum_{i=1}^{M} \beta_i x_i + \beta_0 \qquad \beta's \text{ are estimated by maximum likelihood} - \mathbf{x} \equiv [\mathbf{y}, \mathbf{q}, \mathbf{y} \otimes \mathbf{q}]' \qquad \text{gradient ascent}$$

University of Surrey

Fusion Algorithm (UniS)

Fixed-rule fusion

Divide scores into two groups $\left\{y_{m}^{high}\right\}\left\{y_{n}^{low}\right\}$ according to quality measures then combine with the following rule:

$$y_{com} = \begin{cases} \frac{1}{M} \sum_{m} y_{m}^{high} \times \frac{1}{N} \sum_{n} y_{n}^{low} & \text{if } M > 0 \text{ and } N > 0 \\ \frac{1}{M} \sum_{m} y_{m}^{high} & \text{if } N = 0 \\ \frac{1}{N} \sum_{n} y_{n}^{low} & \text{if } M = 0 \end{cases}$$

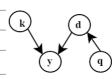
 y_i is high if $q_i > \text{mean}(q_i)$ -std (q_i) ; otherwise y_i is low

University of Surrey

Slide 7

Device-specific Qualitydependent Fusion

$k \in \{\mathtt{C}, \mathtt{I}\}$	Class label (unobserved in test)
$y \in \mathbb{R}^N$	a score (scalar)
$q \in \mathbb{R}^{\mathtt{N}_q}$	Vector of quality measures
$d \in \{1, \dots, \mathtt{N}_d\}$	Device (unobserved in test)



$$y_{\text{with }d}^{norm} = \log \frac{\sum_{d} p(y|\mathbf{C}, d) p(d|q)}{\sum_{d} p(y|\mathbf{I}, d) p(d|q)}$$

digital webcam

where $p(d|q) = \frac{p(q|d)p(d)}{\sum_{\cdot} p(q|d_*)p(d_*)}$





p(y,|k,d) and p(q|d) were estimated using GMM and its number of components was decided using cross-validation on the dev. data set

University of Surrey

Reference: BTAS'07

Sequential Evaluation and Double Thresholding

Albert Salah and Onkar Ambkar

Centrum voor Wiskunde en Informatica (CWI)
The Netherlands

Slide 11

CWI: double-thresholding

$$P(\mathtt{C}|\mathbf{y}) = \frac{p(\mathbf{y}|\mathtt{C})P(\mathtt{C})}{p(\mathbf{y}|\mathtt{C})P(\mathtt{C}) + p(\mathbf{y}|\mathtt{I})P(\mathtt{I})}$$

Where $p(\mathbf{y}|k)$ is an incremental mixture of factor analyzers (IMOFA)

- Evaluate the modalities in the order of face, iris, fingerprint
- If the face or the iris is present, do not take the fingerprints into account
- If the probability of being a genuine user is higher than a threshold (0.5) at any time, output that probability (i.e. accept as genuine) and do not consider the rest of the modalities.
- If the probability of being a genuine user is lower than a threshold (0.025)
- Output that probability (i.e. reject as impostor) and do not consider the rest of the modalities



- Training with only high quality data
- Quality measures are used
- Output « probabilities »

Slide 13



Bayesian Belief Network

John Baker

JHUAPL

BBN For Multi-Modal Fusion

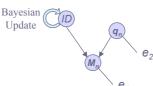
- · Prior probabilities
 - Uniform Initialization:

 $p_{\text{prior}}(ID) = 0.50 \ (ID = non-match, match)$

- Individual Modalities Modeled as Conditionally Independent Given ID
- Multi-Modal Update Equation:

$$p_{\text{update}}(ID) = p_{\text{prior}}(ID) \cdot \underbrace{p(M_n = e_1 \mid ID, q_n = e_2)}_{Norm}$$

- Bayesian Update Iterated for Each Available Measurement (e.g. Each Finger) for Each Modality
 - If Correlation Exists Between Measurements or Modalities, BBN Would Need to Be Altered to Represent Appropriate Conditional Probabilities



Conditional Nodes:

 M_n nth Modality Score q_n nth Modality Quality

Output Nodes:

ID Binary Random Variable

(0 for Non-Match, 1 for Match)

Evidence

e, Measurement for ith Input

$$\begin{split} p(M_n = e_1 \mid ID, q_n = e_2) \quad \text{is the likelihood of} \\ \text{observing measurement M}_n = e_1 \, \text{given} \\ \text{observed quality q}_n = e_2 \, \text{and ID} = \\ \text{Match or Non-Match.} \end{split}$$

Slide 15

Other Presentations



✓ JR

UPM

AMSL